



Transformer Network for Event/Particle Identification and Interpretability at NOvA

Jianming Bian

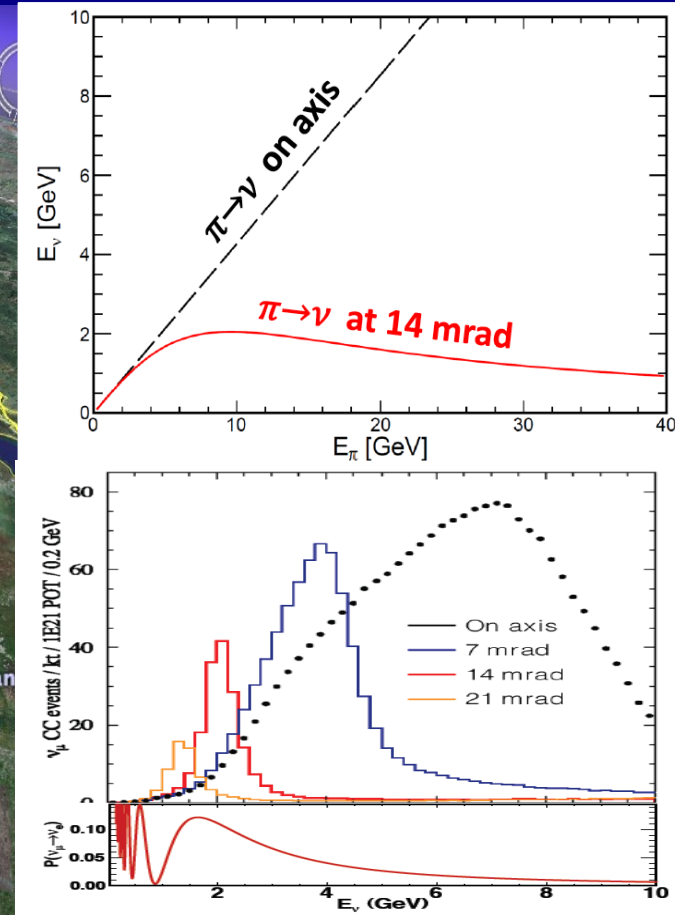
University of California, Irvine

for the NOvA Collaboration

06-25-2024

NPML 2024, ETH Zurich, Switzerland

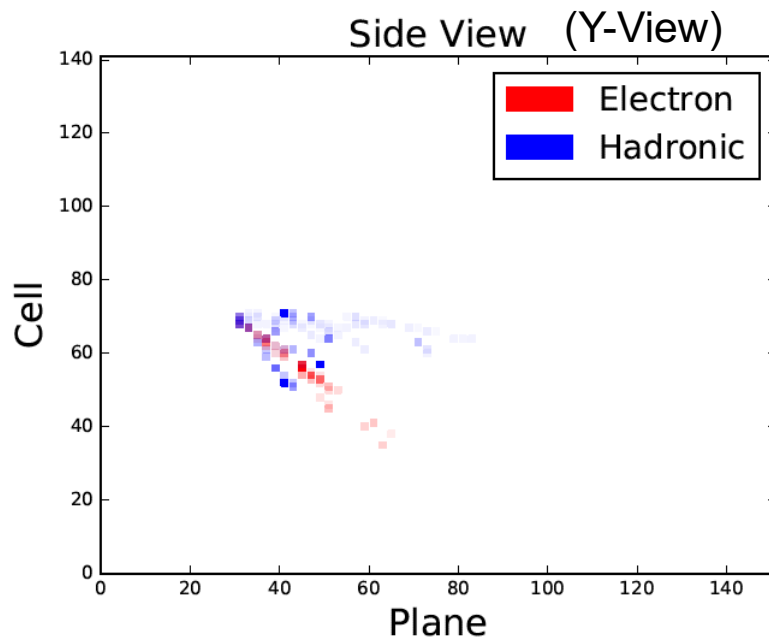
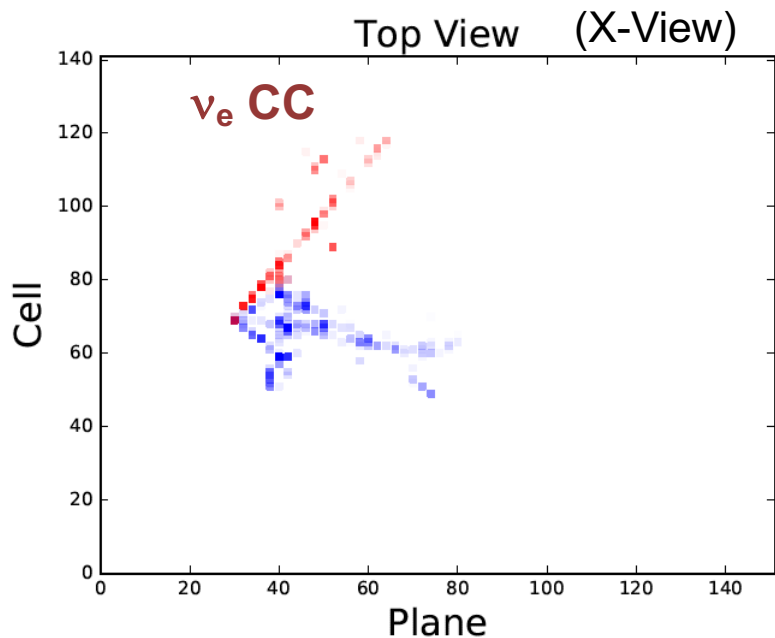
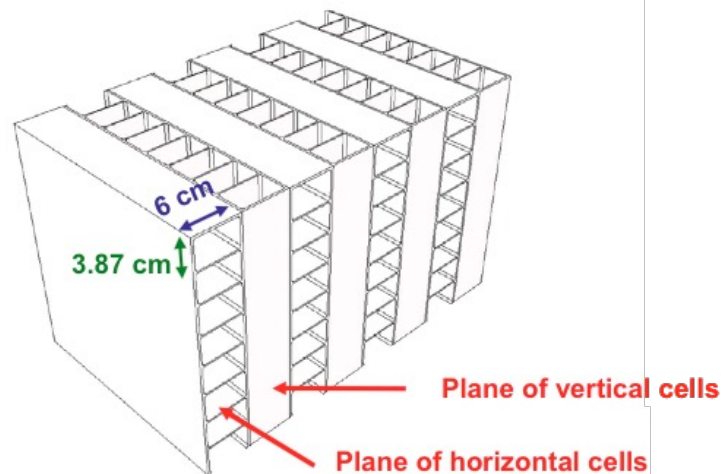
NuMI Off-Axis ν_e Appearance Experiment (NOvA)



- Muon neutrino beam at Fermilab near Chicago
- Longest baseline in operation (810 km), large matter effect, sensitive to mass ordering
- Far/Near detector sited 14 mrad off-axis, narrow-band beam around oscillation maximum

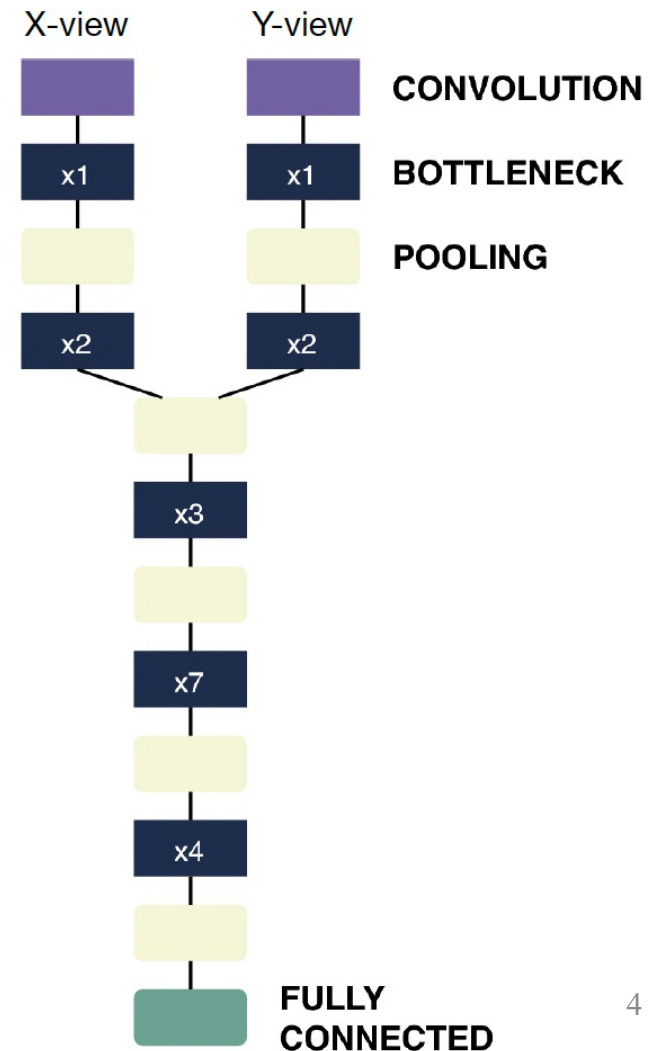
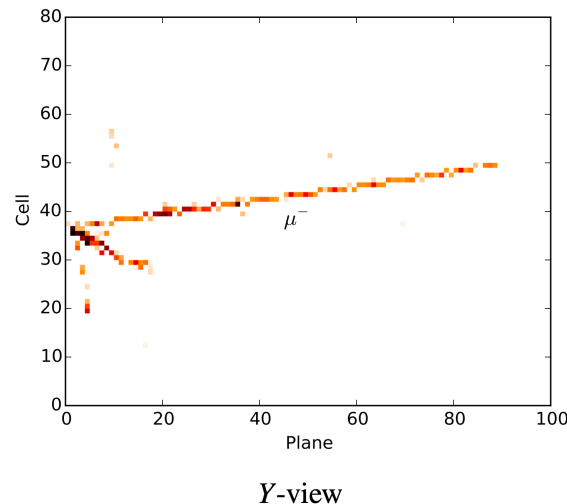
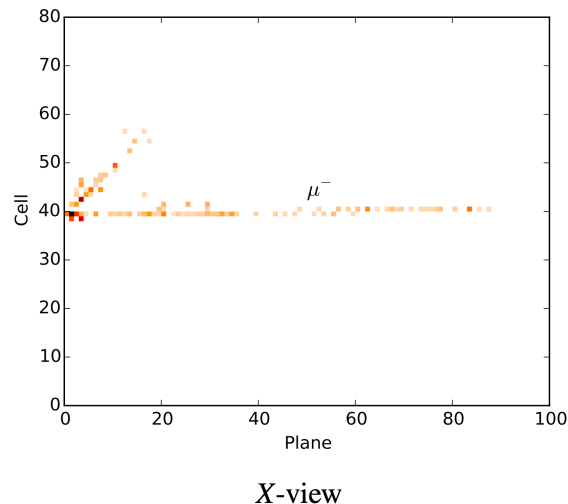
NOvA Event Images

- NOvA detector cells arranged in planes, assembled in alternating X and Y directions
- Produce a pair of pixel maps (Cell Number vs. Plane Number) for the X and Y view of each interaction
- NOvA's 2-view pixel maps are ideal for image processing neural networks to reconstruct neutrino events



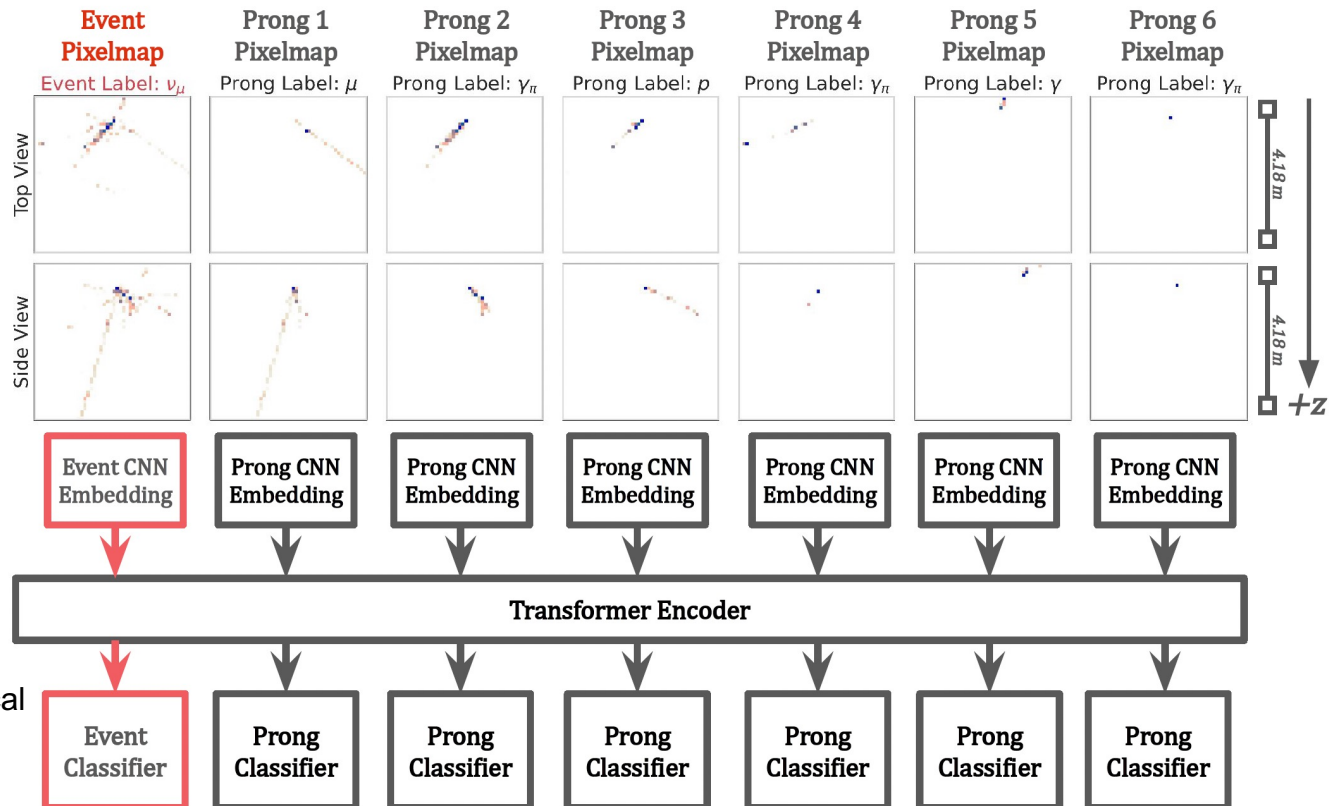
EventCVN and ProngCVN

- EventCVN: neutrino event selection CNN trained on cropped XZ and YZ event images (pixel maps). Predicts [ν_μ CC, ν_e CC, NC, cosmic], used since 2017 [JINST 11, P09001 (2016), Phys.Rev.Lett. 118 (2017)]
- ProngCVN: predicts final state particle type from prong-only images and event images



TransformerCVN for Event and Particle Identification

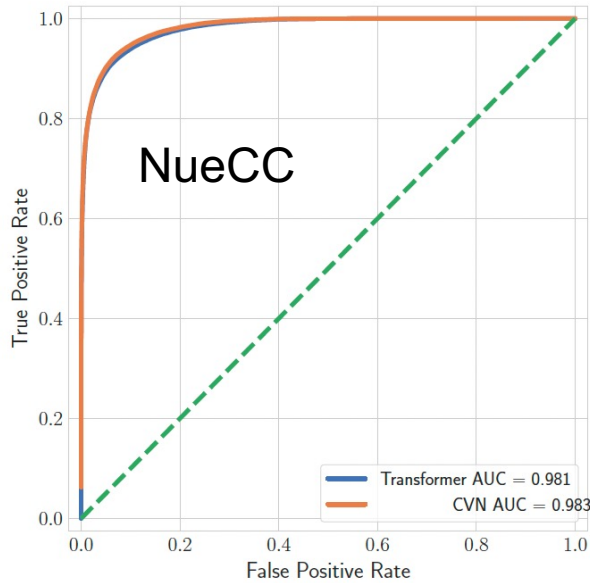
- Transformer: attention based network, foundation of ChatGPT, ideal for training on variable-length collection of object such as prongs
- Uses both event and prong images as inputs, identifies neutrino flavor and each particle simultaneously.
- Attention mechanisms automatically focus training and evaluation on image regions important to the final decision, significantly reducing the computing burden and enhancing training performance
- Attention mechanisms also provides interpretability, making deep learning more than just a “black box”



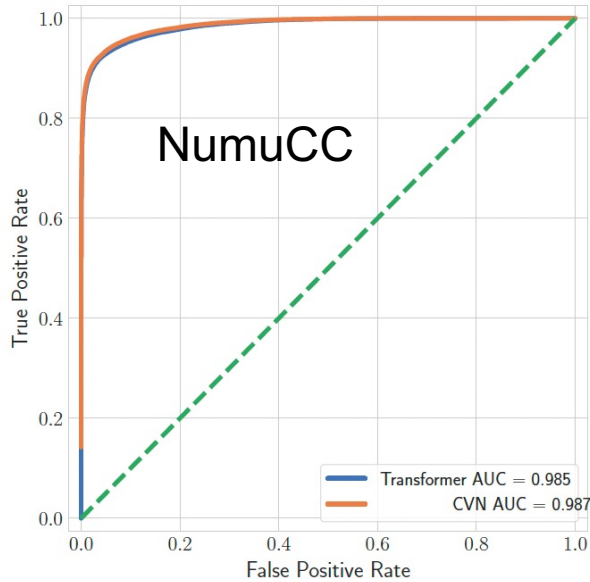
Transformer+CNN
="TransformCVN"

Event and Prong ROC Curves

TransformerCVN/Event CVN

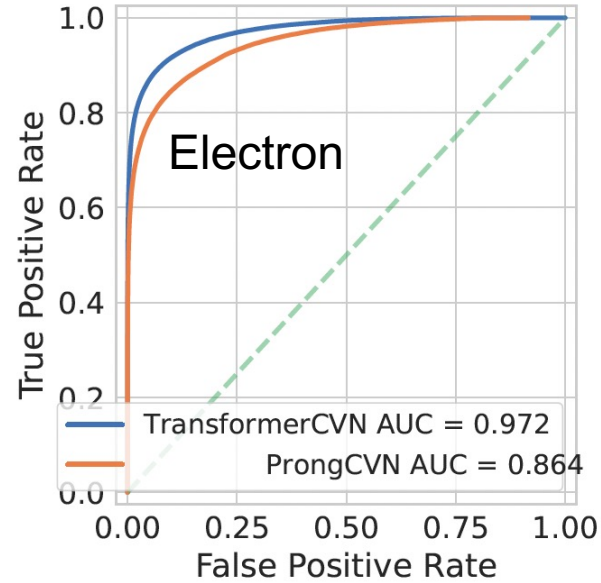


(a) ROC Curve for ν_e event reconstruction.

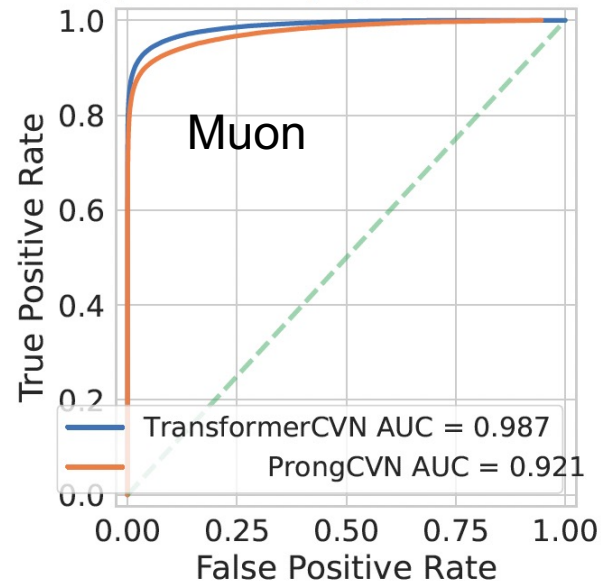


(b) ROC Curve for ν_μ event reconstruction.

TransformerCVN/Prong CVN

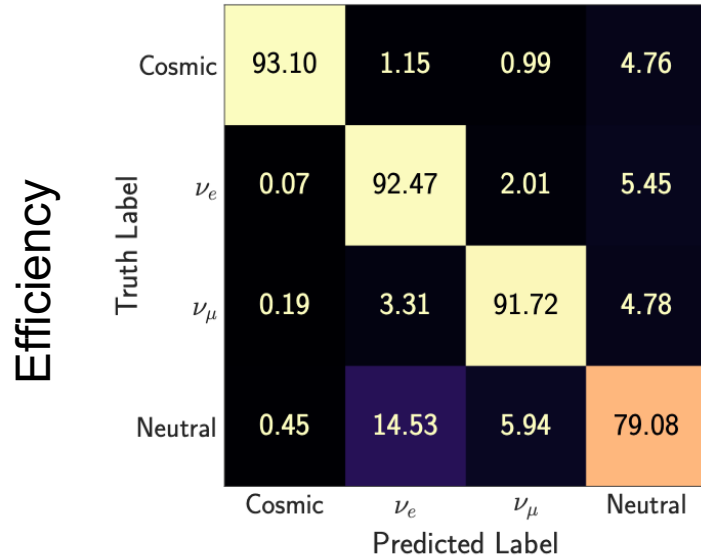


(a) ROC Curve for e prong reconstruction.

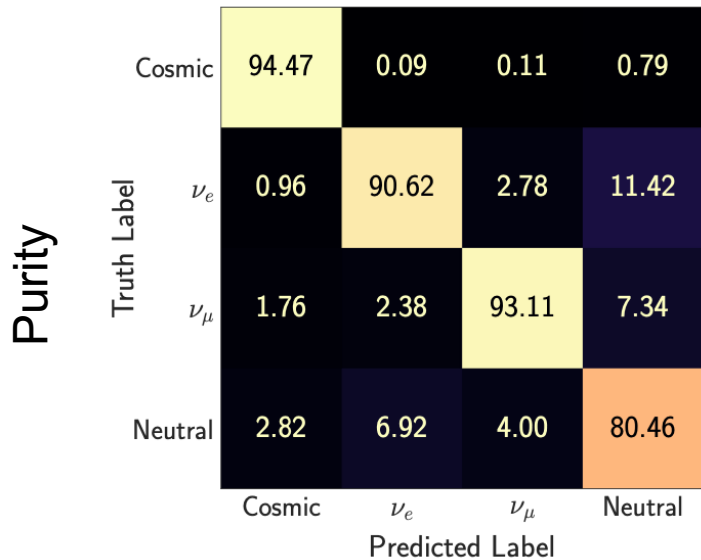


(b) ROC Curve for μ prong reconstruction.

Event Confusion Matrices

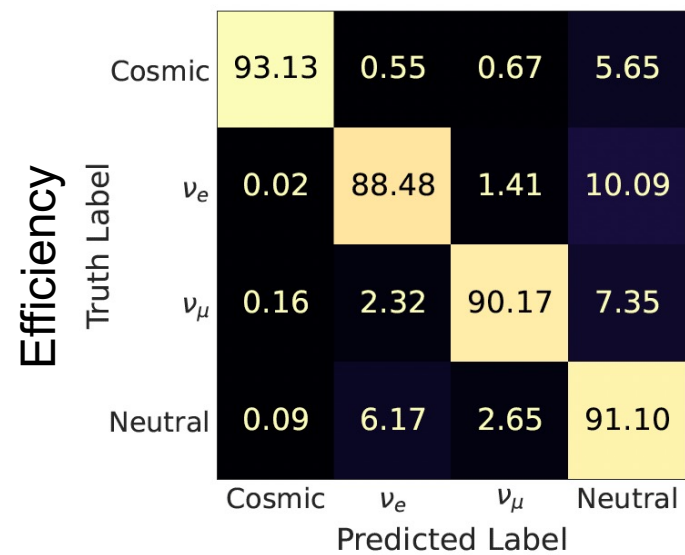


(a) Efficiency matrix, normalized along truth labels.

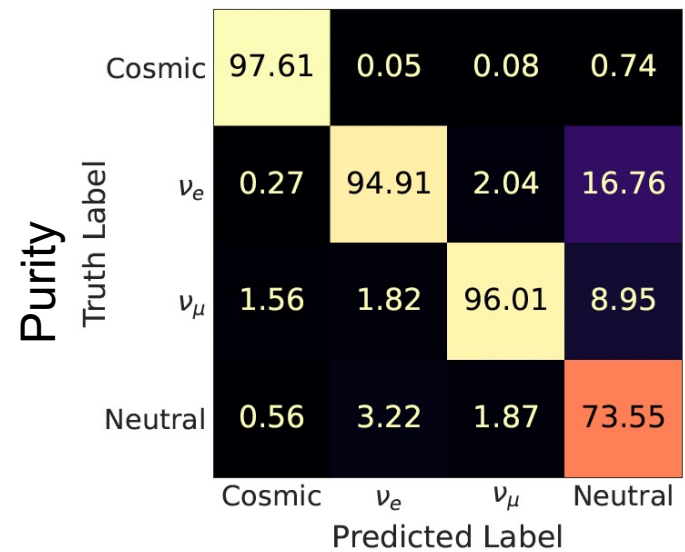


(b) Purity matrix, normalized along predictions.

TransformerCVN



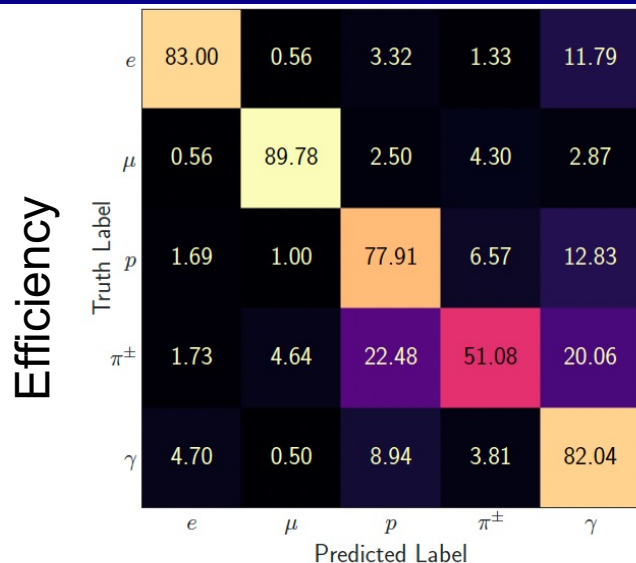
(a) Efficiency matrix, normalized along truth labels.



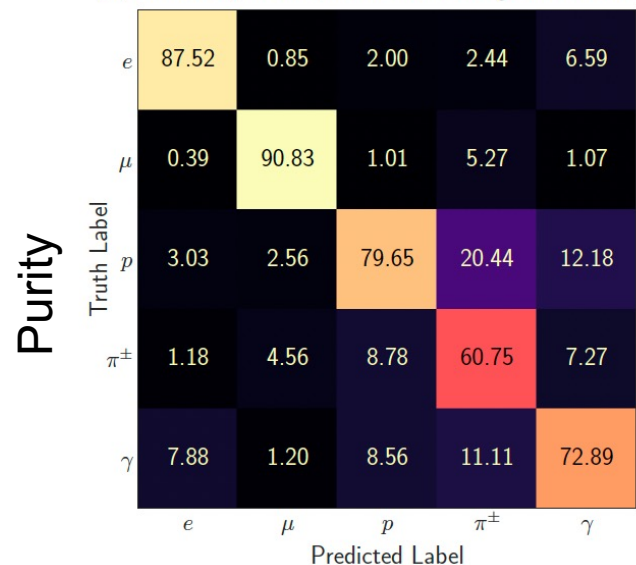
(b) Purity matrix, normalized along predictions.

Event CVN

Prong Confusion Matrices

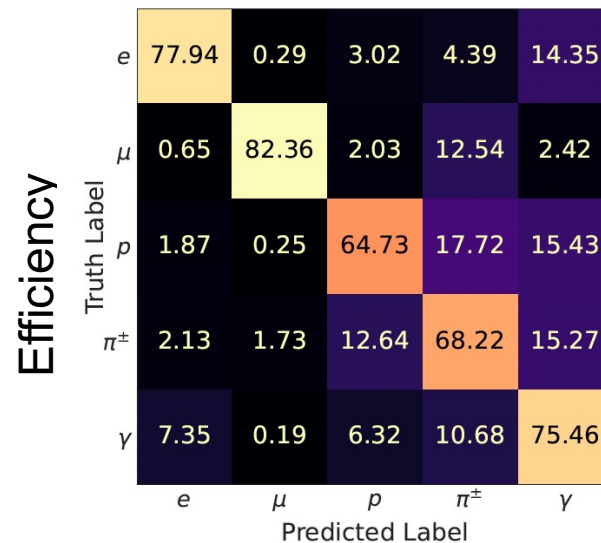


(a) Efficiency matrix, normalized along truth labels.

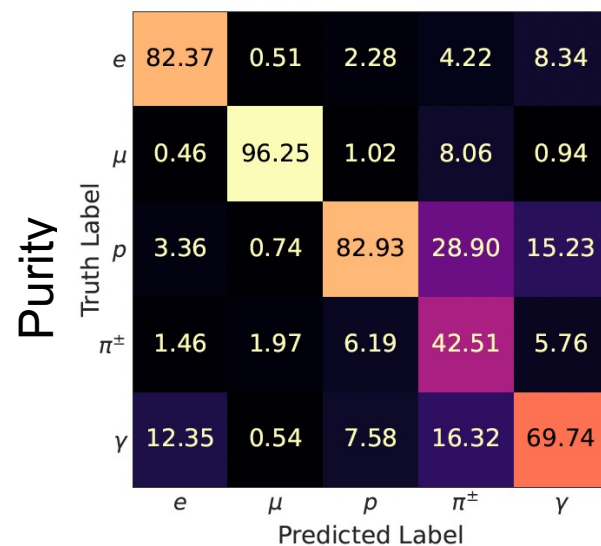


(b) Purity matrix, normalized along predictions.

TransformerCVN



(a) Efficiency matrix, normalized along truth labels.



(b) Purity matrix, normalized along predictions.

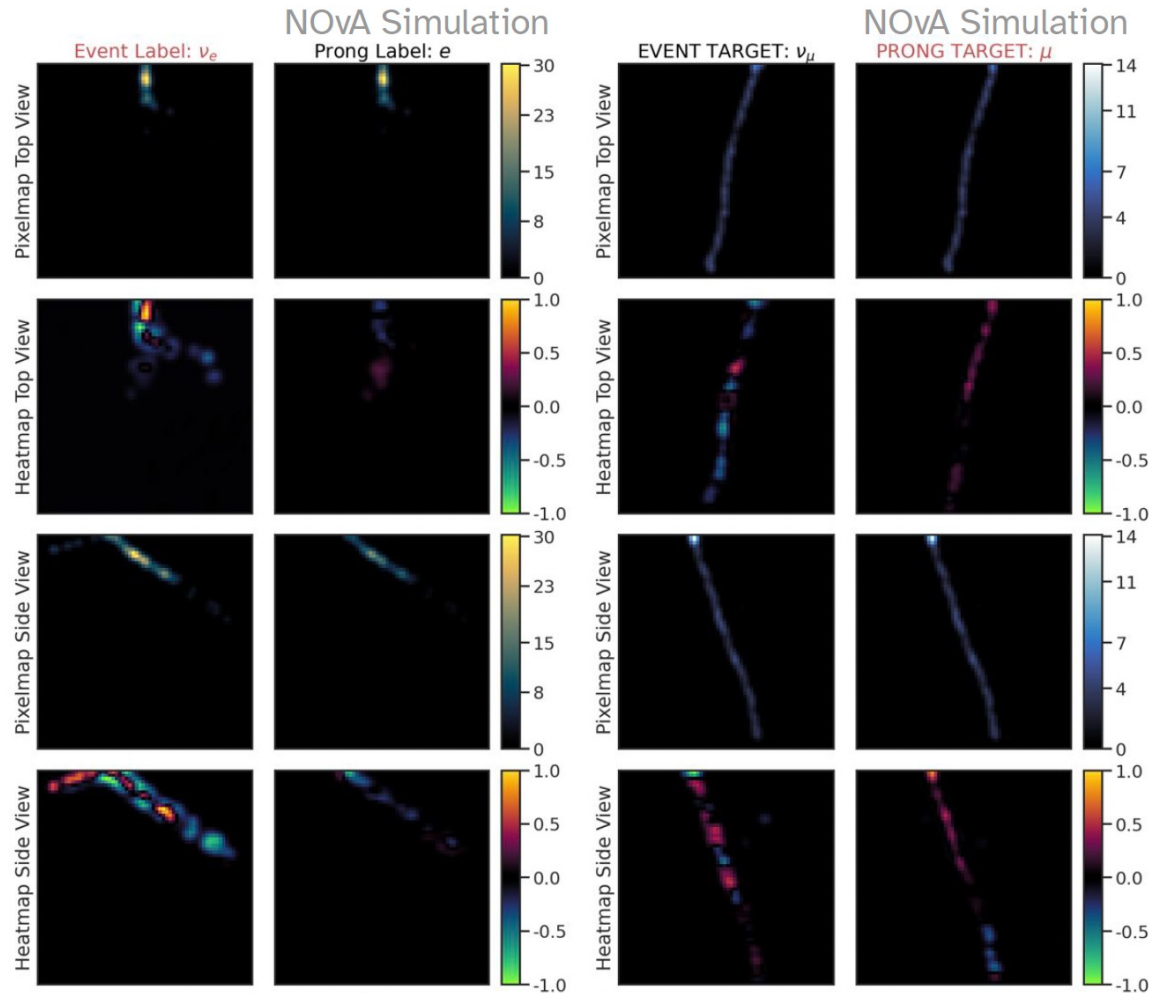
ProngCVN

Interpretability

- Pixel Gradients (Saliency)
 - Saliency: gradient of output classification probability with respect to change in each hit
 - Attention mechanism enhances the saliency of key regions in the input
 - Study saliency to understand which regions the Transformer focuses on to identify a particle
 - When aggregated, provides a template of a typical pattern for each prong type
- Attention Scores
 - Indicate the importance of different elements to the output
 - Allows us to find out which prongs are most useful to identify different types of events
 - Diagnose neural network and explain decision

Individual Saliency

- Calculate saliency of different hits for each event
- Useful for debugging wrong predictions
- Need to aggregate multiple prongs of the same type to find patterns



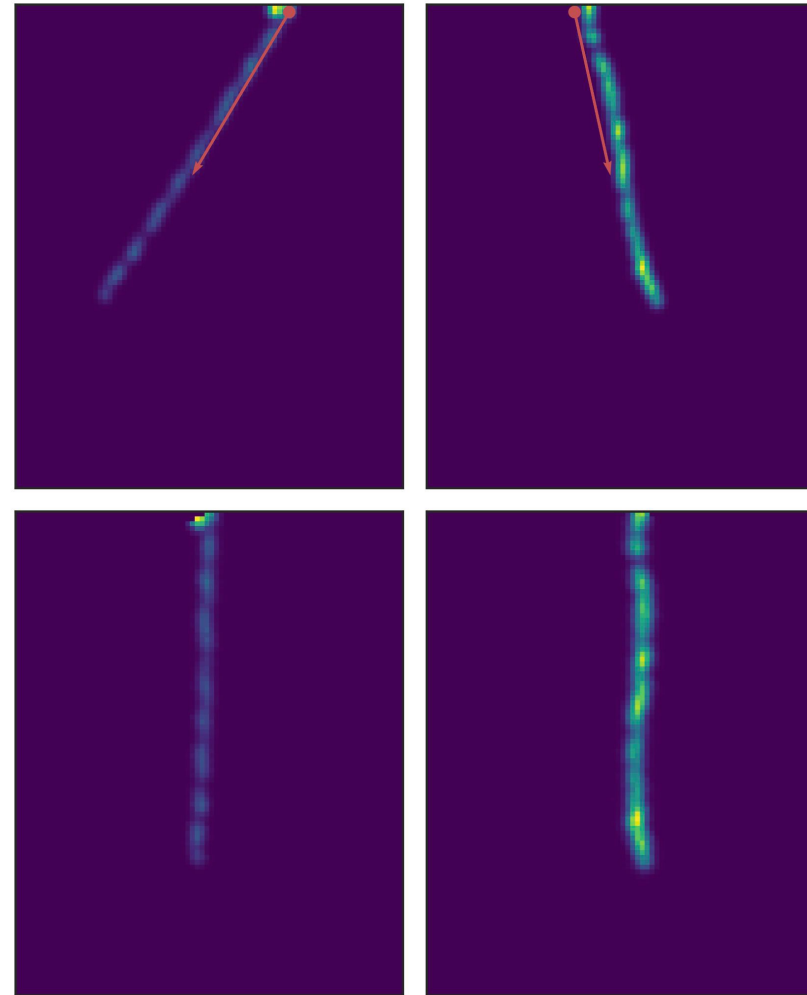
Red: more likely to predict the given flavor/particle type with more energy in that location.

Green: less likely to predict if there is more activity (anti-correlation).

Saliency Aggregation

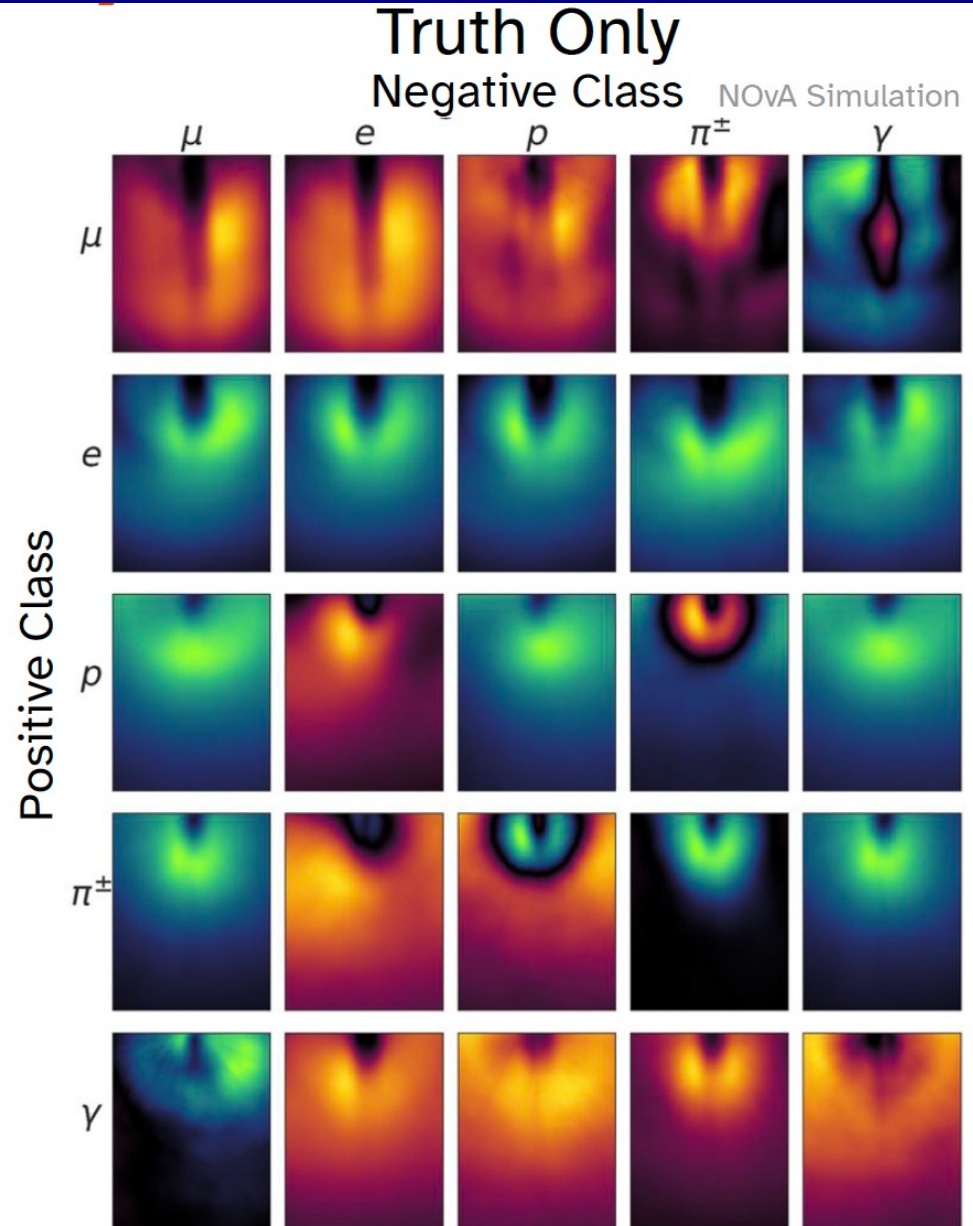
- Calculated average saliency values for each type of particle in $\sim 10,000$ events
- Rotated and translated each prong image using the vertex and direction information associated with each prong.
 - Every prong forced to have vertex at $(40, 0)$ and facing toward $+z$.
 - Possibly limit event by track length to compare similar lengths.
- New tool to analyze saliency pattern

Pixel Map Alignment



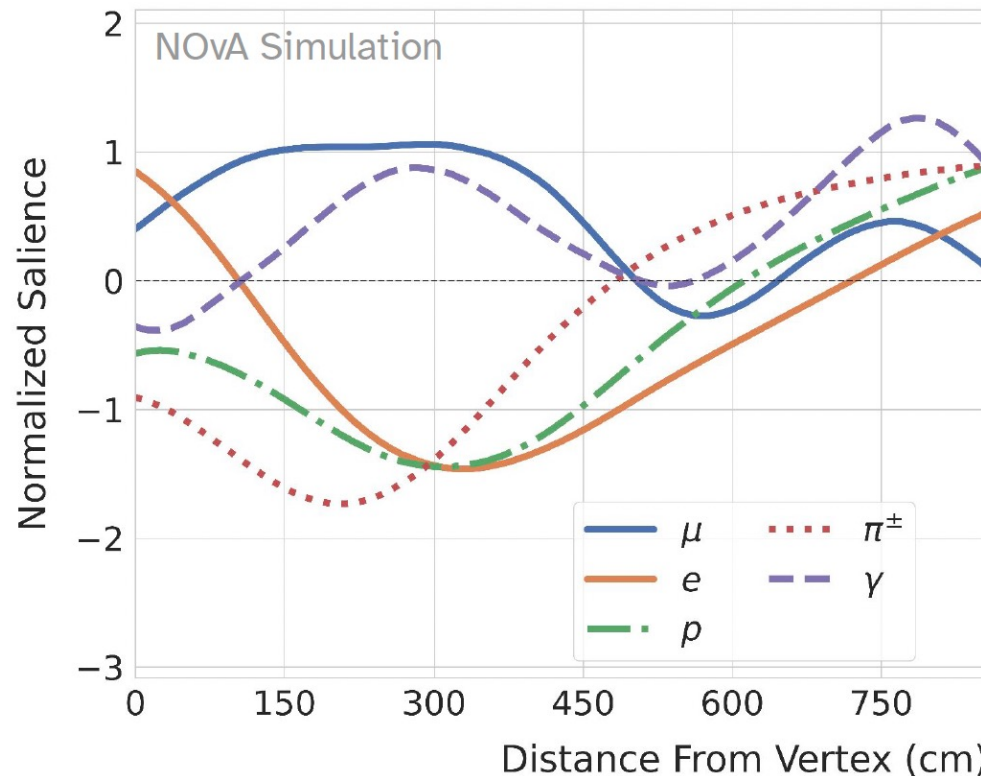
Saliency Aggregation

- Truth-Only plots contain only prongs whose truth label matches the Positive Class.
- Diagonal displays the gradients for each class.
- Off-Diagonal elements display Positive Class Saliency - Negative Class Saliency



Integrated Saliency Maps

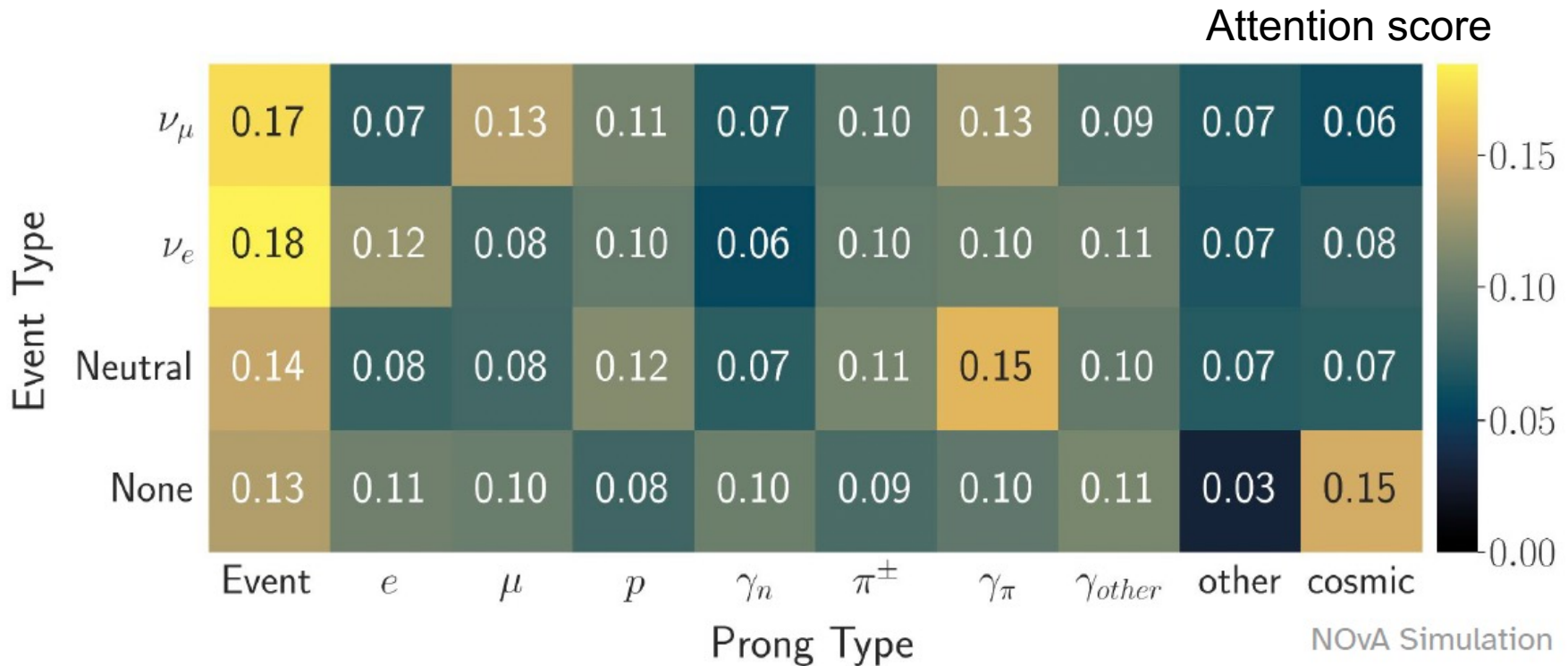
- Comparing 2D maps is challenging, so integrate importance along the width of the detector and plot them all on the same axis w.r.t distance from the vertex
 - Electrons peak early, fall off.
 - Muons have a long, flat profile along track.
 - Photons feature delayed peak.
 - Tail values (>500 cm) tend to go wild due to sparse data in that region



Attention Matrix

Importance of different prong types for classifying the event type

- e, μ important for corresponding CC events.
- p and π^0 important for NC.



Summary

- “TransformerCVN” architecture has been developed for joint event/particle classification
- Performance comparable or better than traditional CNN
- Use Saliency to identify shower/track regions that are important to the final decision
- Use Attention scores to interpret relationships between output event and particle classifications

Thank you!